



臺灣大學

# Iteration Bound

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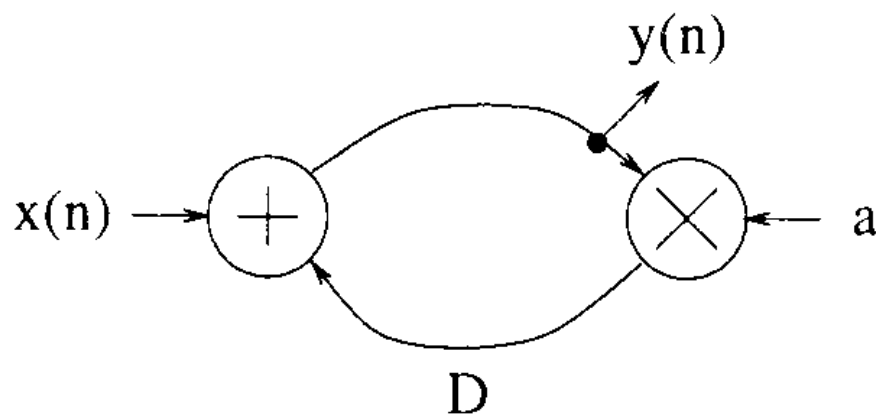
# Iteration Bound $T_{\infty}$

- Only for recursive algorithms which have feedback loops
- Impose an inherent fundamental lower bound on the achievable iteration or sample period
- A characteristic of data-flow graph (DFG)
- Two methods to calculate iteration bound
  - Longest path matrix (LPM)
  - Minimum cycle mean (MCM)

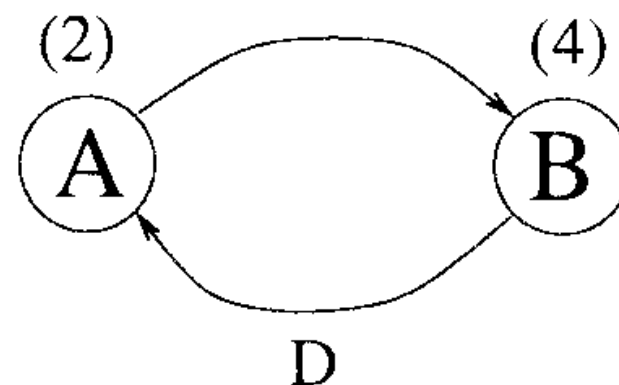
# Data-Flow Graph Representations (1/2)

for  $n = 0$  to  $\infty$

$$y(n) = ay(n-1) + x(n)$$



Block diagram



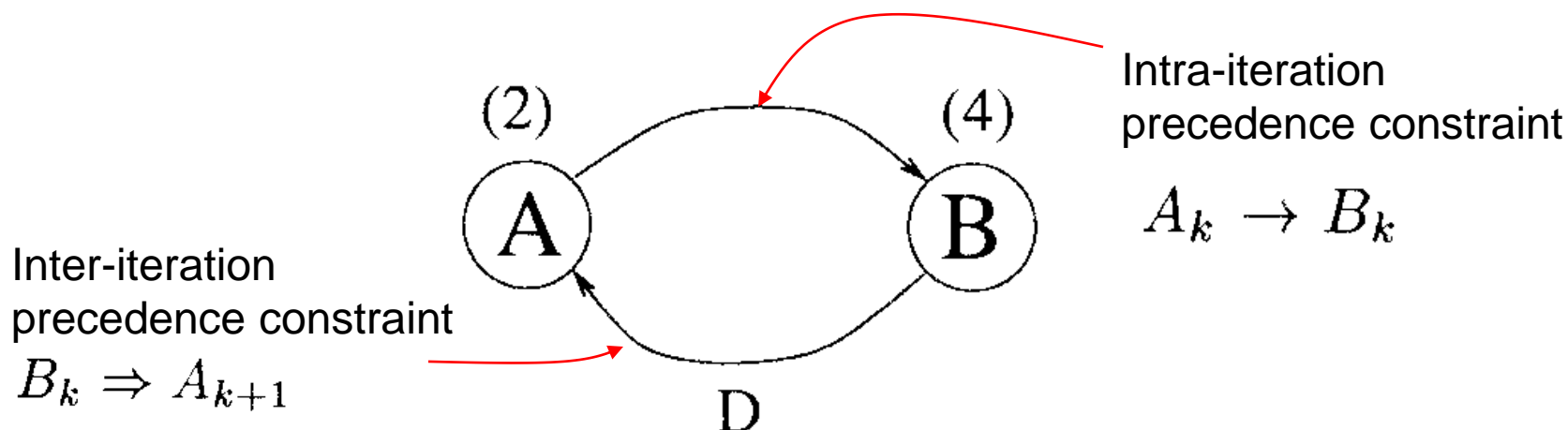
Data-flow graph (DFG)

# Data-Flow Graph Representations (2/2)

## ■ Iteration

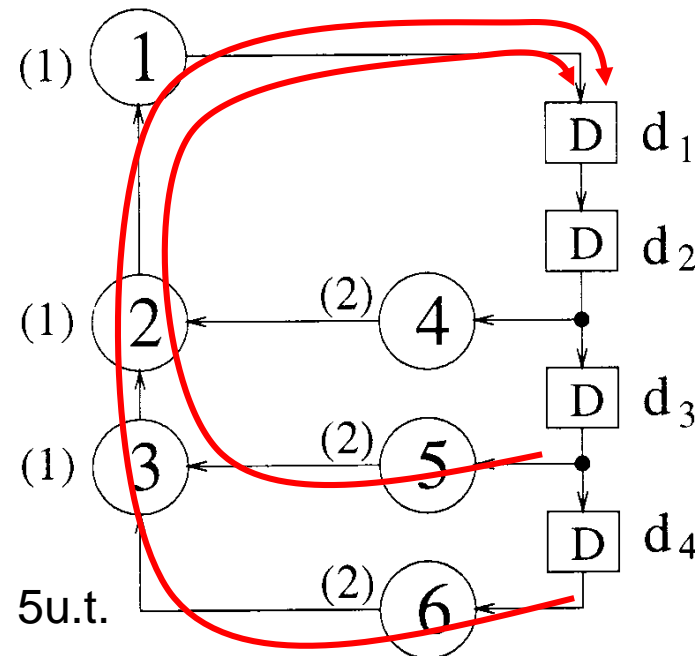
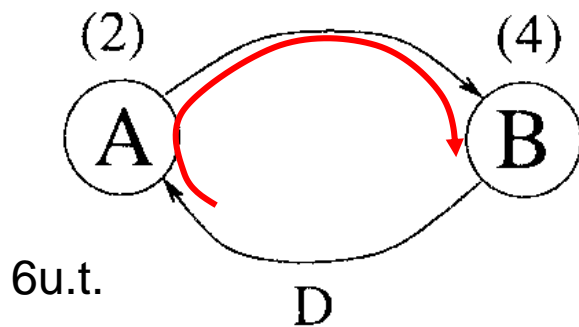
- Execution of each node in the DFG exactly once
- $X_k$ : k-th iteration of node X

## ■ Precedence constraints



# Critical Path

- The path with the longest computation time among all paths that contain zero delays

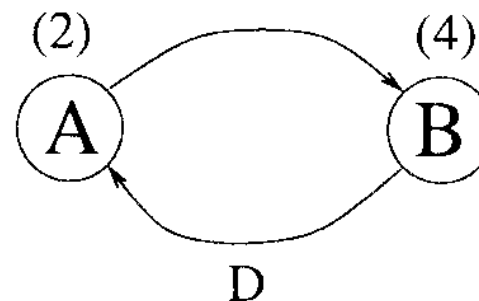


# Loop Bound (1/2)

## ■ Loop (cycle)

- A directed path that begins and ends at the same node

$$A \rightarrow B \rightarrow A$$



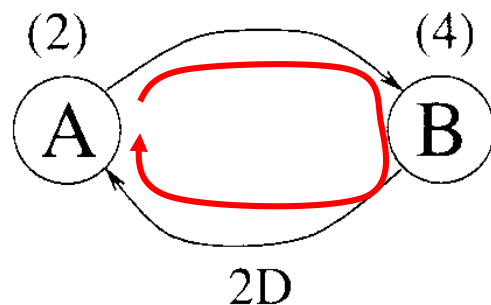
## ■ Precedence constraints

$$A_0 \rightarrow B_0 \Rightarrow A_1 \rightarrow B_1 \Rightarrow A_2 \rightarrow B_2 \Rightarrow A_3 \rightarrow \dots$$

# Loop Bound (2/2)

## ■ Loop bound

- The lower bound on the loop computation time
- Loop bound of  $l$ -th loop:  $t_l/w_l$
- $t_l$ : loop computation time
- $w_l$ : the number of delays in the loop



$$6/2=3 \text{ u.t.}$$

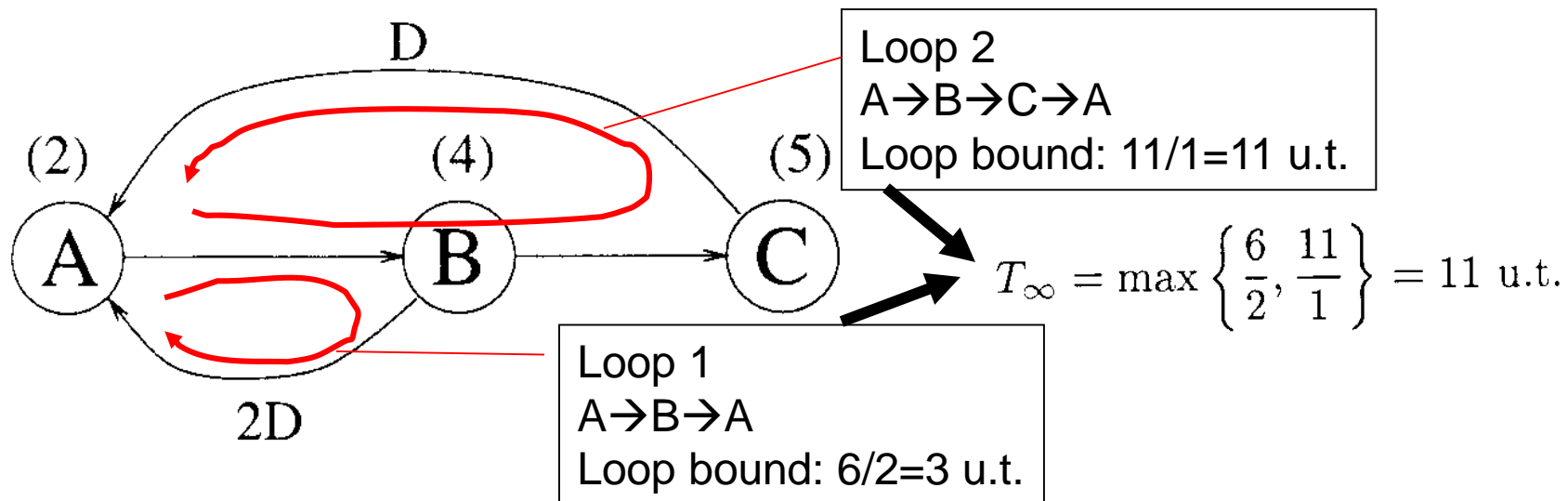
$$A_0 \rightarrow B_0 \Rightarrow A_2 \rightarrow B_2 \Rightarrow A_4 \rightarrow B_4 \Rightarrow A_6 \rightarrow \dots$$

$$A_1 \rightarrow B_1 \Rightarrow A_3 \rightarrow B_3 \Rightarrow A_5 \rightarrow B_5 \Rightarrow A_7 \rightarrow \dots$$

# Iteration Bound (1/3)

- Critical loop
  - The loop with the maximum loop bound
- Iteration bound
  - Loop bound of the critical loop

$$T_{\infty} = \max_{l \in L} \left\{ \frac{t_l}{w_l} \right\}$$

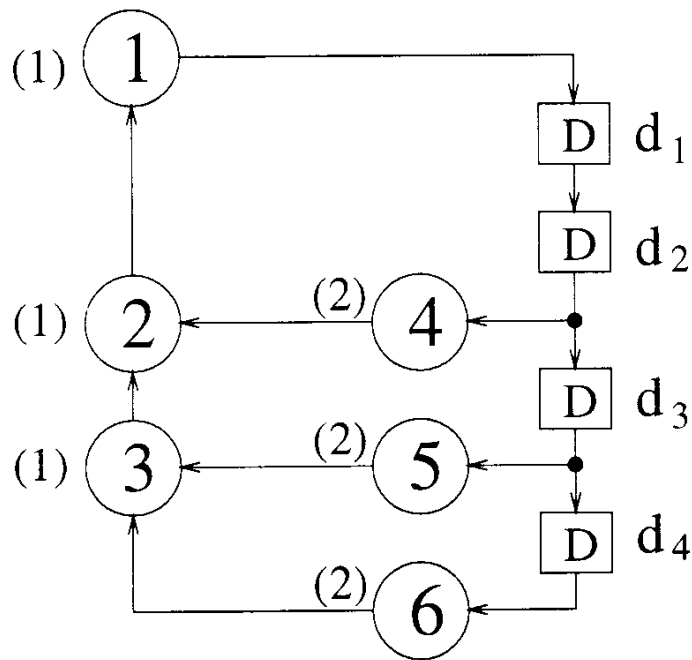






# Iteration Bound (2/3)

## ■ An other example



L1: 1→4→2→1

L2: 1→5→3→2→1

L3: 1→6→3→2→1

$$T_{\infty} = \max \left\{ \frac{4}{2}, \frac{5}{3}, \frac{5}{4} \right\} = 2 \text{ u.t.}$$



# Iteration Bound (3/3)

- **Iteration bound** is the lower bound on the iteration or sample period of the DSP program regardless of the amount of computing resources available



# Algorithms for Computing Iteration Bound

- Longest path matrix algorithm
  - We only introduce this one
- Minimum cycle mean algorithm
- Negative cycle detection algorithm

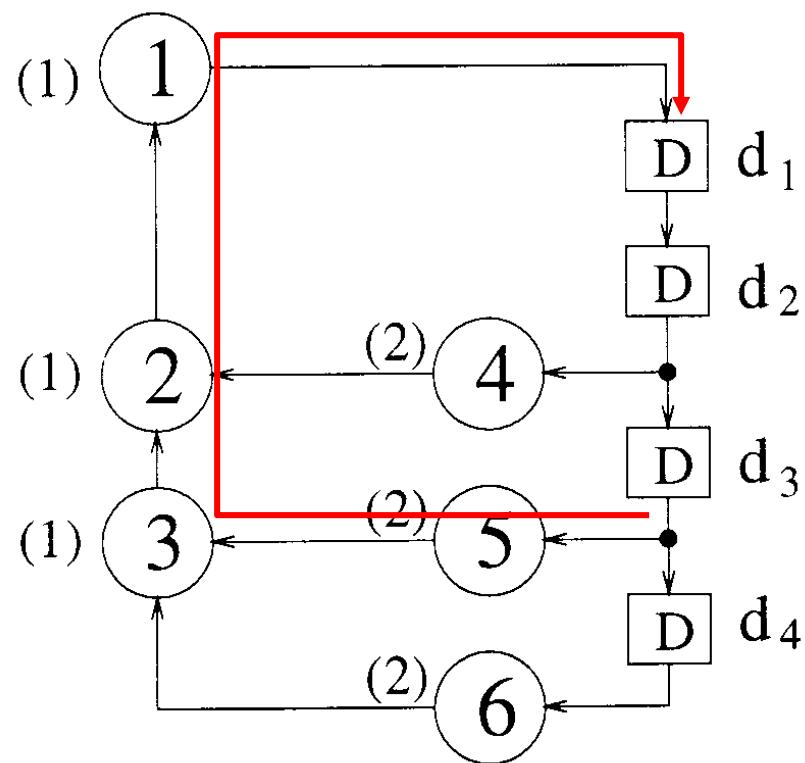


# Longest Path Matrix Algorithm (LPM) (1/8)

- There are  $d$  delay elements in the DFG
- First, construct a series of matrices  $L^{(m)}$ ,  $m=1,2,\dots,d$
- $l_{i,j}^{(m)}$ 
  - Longest computation time of all paths from delay element  $d_i$  to  $d_j$  that pass through exactly  $m-1$  delays
  - If no such path exists, then  $l_{i,j}^{(m)} = -1$

# LPM (2/8)

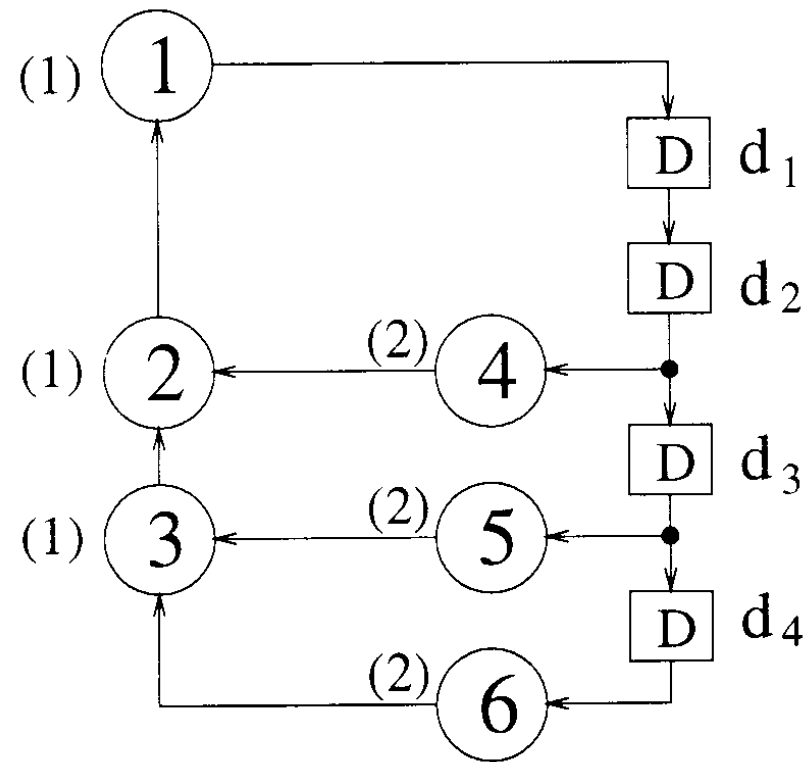
- Ex:
- $I_{3,1}^{(1)}$ 
  - $d_3 \rightarrow n_5 \rightarrow n_3 \rightarrow n_2 \rightarrow n_1 \rightarrow d_1$
  - So  $I_{3,1}^{(1)} = 5$
- $I_{4,3}^{(1)}$ 
  - No such path (2 delays, at least)
  - So  $I_{4,3}^{(1)} = -1$





# LPM (3/8)

$$\mathbf{L}^{(1)} = \begin{array}{c} \text{O/P} \\ \text{I/P} \end{array} \begin{array}{c} d1 \\ d2 \\ d3 \\ d4 \end{array} \begin{bmatrix} -1 & 0 & -1 & -1 \\ 4 & -1 & 0 & -1 \\ 5 & -1 & -1 & 0 \\ 5 & -1 & -1 & -1 \end{bmatrix}$$





# LPM (4/8)

## ■ The higher order matrices

□ Can be derived from  $L^{(1)}$

□ 
$$l_{i,j}^{(m+1)} = \max_{k \in K} (-1, l_{i,k}^{(1)} + l_{k,j}^{(m)})$$

□  $K$  is the set of integers  $k$  in the interval  $[1, d]$  such that neither  $l_{i,k}^{(1)} = -1$  nor  $l_{k,j}^{(m)} = -1$  holds



# LPM (5/8)

■ Ex:

■  $l_{2,1}^{(2)}$

$$\mathbf{L}^{(1)} = \begin{matrix} & \text{O/P} & d1 & d2 & d3 & d4 \\ \text{I/P } d1 & \begin{bmatrix} -1 & 0 & -1 & -1 \end{bmatrix} \\ d2 & \begin{bmatrix} 4 & -1 & 0 & -1 \end{bmatrix} \\ d3 & \begin{bmatrix} 5 & -1 & -1 & 0 \end{bmatrix} \\ d4 & \begin{bmatrix} 5 & -1 & -1 & -1 \end{bmatrix} \end{matrix} \quad \mathbf{l}_{i,k}^{(1)} = \begin{matrix} -4 & -1 \\ -1 & 4 \\ 0 & 5 \\ -1 & 5 \end{matrix}$$

$$\begin{aligned} l_{2,1}^{(2)} &= \max_{k \in \{3\}} (-1, l_{2,k}^{(1)} + l_{k,1}^{(1)}) \\ &= \max(-1, 0 + 5) = 5. \end{aligned}$$





# LPM (6/8)

- L1, L1 → L2
- L1, L2 → L3
- L1, L3 → L4

$$\mathbf{L}^{(2)} = \begin{bmatrix} 4 & -1 & 0 & -1 \\ 5 & 4 & -1 & 0 \\ 5 & 5 & -1 & -1 \\ -1 & 5 & -1 & -1 \end{bmatrix}$$

$$\mathbf{L}^{(3)} = \begin{bmatrix} 5 & 4 & -1 & 0 \\ 8 & 5 & 4 & -1 \\ 9 & 5 & 5 & -1 \\ 9 & -1 & 5 & -1 \end{bmatrix}$$

$$\mathbf{L}^{(4)} = \begin{bmatrix} 8 & 5 & 4 & -1 \\ 9 & 8 & 5 & 4 \\ 10 & 9 & 5 & 5 \\ 10 & 9 & -1 & 5 \end{bmatrix}$$



# LPM (7/8)

- Iteration bound:

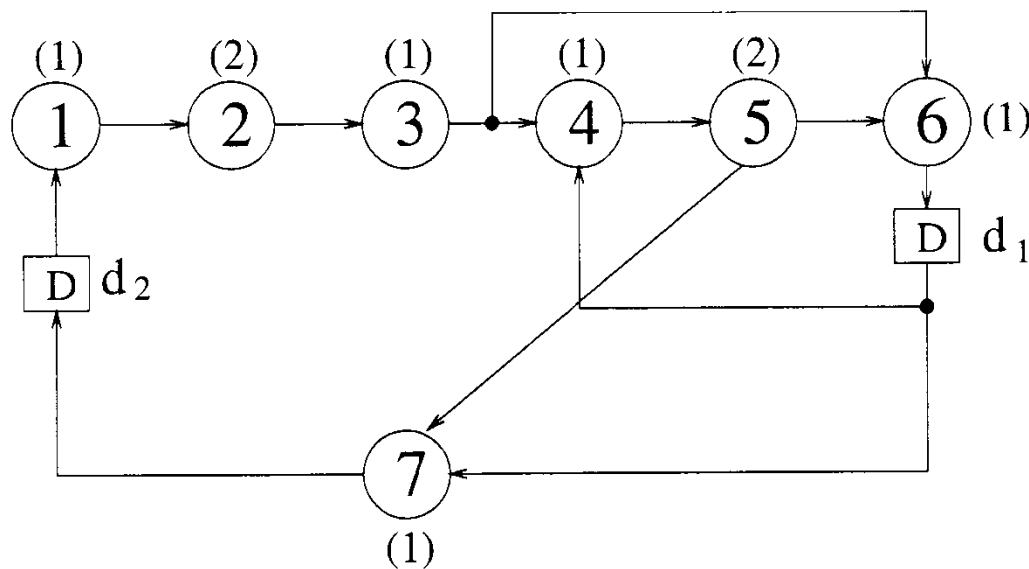
$$T_{\infty} = \max_{i, m \in \{1, 2, \dots, d\}} \left\{ \frac{l_{i,i}^{(m)}}{m} \right\}$$

$$T_{\infty} = \max \left\{ \frac{4}{2}, \frac{4}{2}, \frac{5}{3}, \frac{5}{3}, \frac{5}{3}, \frac{8}{4}, \frac{8}{4}, \frac{5}{4}, \frac{5}{4} \right\} = 2.$$



# LPM (8/8)

## ■ An other example



$$\mathbf{L}^{(1)} = \begin{bmatrix} 4 & 4 \\ 8 & 8 \end{bmatrix}$$

$$\mathbf{L}^{(2)} = \begin{bmatrix} 12 & 12 \\ 16 & 16 \end{bmatrix}$$

$$T_{\infty} = \max \left\{ \frac{4}{1}, \frac{8}{1}, \frac{12}{2}, \frac{16}{2} \right\} = 8.$$